#### **General data**

#### Overview

The advantages of the SIRIUS soft starters at a glance:
• Soft starting and smooth ramp-down 1)

- Stepless starting
- Reduction of current peaks
- Avoidance of mains voltage fluctuations during starting
- Reduced load on the power supply network

- Reduction of the mechanical load in the operating mechanism
- Considerable space savings and reduced wiring compared with conventional starters
- Maintenance-free switching
- Very easy handling
- Fits perfectly in the SIRIUS modular system









		Mills.		t and and and the second
		SIRIUS 3RW30/31 Standard applications	SIRIUS 3RW40 Standard applications	SIRIUS 3RW44 High-Feature applications
Rated current up to 40 °C	Α	3 100	12.5 432	29 1214
Rated operational voltage	V	200 575	200 600	200 690
Motor rating at 400 V Inline circuit Inside-delta circuit	kW kW	1.1 55 	5.5 250	15 710 22 1200
Temperature range	°C	-25 +60	-25 +60	0 +60
Soft starting/ramp-down		<b>✓</b> ¹)	✓	V
Voltage ramp		<i>'</i>	v	<i>y</i>
Starting/stopping voltage	%	40 100	40 100	20 100
Starting and ramp-down time	S	0 20	0 20	1 360
Torque control		-		V
Starting/stopping torque	%			20 100
Torque limit	%			20 200
Ramp time	s			1 360
Integral bypass contact system		<b>√</b> <sup>2)</sup>	V	V
Intrinsic device protection			<b>✓</b>	<b>✓</b>
Motor overload protection			<b>✓</b>	<b>✓</b>
Thermistor motor protection			<b>√</b> <sup>3)</sup>	<b>✓</b>
Integrated remote RESET			<b>✓</b> <sup>4)</sup>	<b>✓</b>
Adjustable current limiting			V	V
Inside-delta circuit				V
Breakaway pulse				V
Creep speed in both directions of rotation				<b>V</b>
Pump ramp-down				<b>√</b> 5)
DC braking				<b>√</b> 5) 6)
Combined braking				<b>✓</b> <sup>5) 6)</sup>
Motor heating				<b>V</b>
Communication				With PROFIBUS DP (optional)
External display and operator modules				(optional)
Operating measured value display				<b>V</b>
Error logbook				<i>V</i>
Event list				<i>V</i>
Slave pointer function Trace function				<b>√</b> <sup>7)</sup>
				V .
Programmable control inputs and outputs  Number of parameter sets		1 (2 with 3RW31)	1	3
Parameterization software (Soft Starter ES)				3 <b>✓</b>
Power semiconductors (thyristors)		2 controlled phases	2 controlled phases	3 controlled phases
Spring-loaded terminals		✓ (only 3RW30 03)	∠ controlled phases	✓ Controlled phases
Screw terminals		(Offig 511W50 05)	<u>,                                     </u>	<u> </u>
UL/CSA		<b>/</b> 8)	·	V
CE marking		<u>,                                     </u>	7	<i>y</i>
Soft starting under heavy starting condition	s	<u>-</u>		<b>√</b> 5)
Configuring compart		Mr. 0 6 0 1 1 1 1		

Configuring support

Win-Soft Starter, electronic selection slider ruler, Technical Assistance +49 911 895 5900

- ✔ Function is available; -- Function is not available.
- Only soft starting available for 3RW30 ..-1AA12 and 3RW31.
   Not available for 3RW30 03.
- 3) Optional up to size S3 (device variant).
- 4) Available for 3RW40 2. to 3RW40 4.; optional for 3RW40 5. and 3RW40 7...
- 5) Calculate soft starter and motor with size allowance where required.
- 6) Not possible in inside-delta circuit.
  7) Trace function with Soft Starter ES software.
- 8) For 3RW30 03 up to 230 V.

More information can be found on the Internet at http://www.siemens.com/softstarter

#### 3RW40 for standard applications

#### Overview

SIRIUS 3RW40 soft starters offer all the same advantages as the 3RW30 soft starters. This also applies to the integrated bypass contact system. At the same time they come with additional functions, e.g. solid-state motor overload and intrinsic device protection and adjustable current limiting, optional thermistor motor protection (up to size S3), integrated remote RESET (up to size S3), as well as a two-phase control method (Polarity Balancing) that is unique in this performance range.

SIRIUS 3RW40 soft starters are part of the SIRIUS modular system. This results in advantages such as identical sizes and a uniform connection method. Thanks to their particularly compact design, SIRIUS 3RW40 soft starters are only half as big as comparable wye-delta starters. Hence they can be mounted in minimum space in the control cabinet. Configuring and mounting are carried out quickly and easily thanks to the 3-wire connection.

#### SIRIUS 3RW40 for three-phase motors

Soft starters rated up to 250 kW (at 400 V) for standard applications in three-phase networks. Extremely small sizes, low power losses and simple commissioning are just three of the many advantages of the SIRIUS 3RW40 soft starters.

#### Function

SIRIUS 3RW40 soft starters have all the same advantages as the 3RW30/31 soft starters. At the same time they come with additional functions and a two-phase control method (Polarity Balancing) that is unique in the performance range up to 250 kW. Starting voltage, starting and ramp-down time of the voltage ramp and current limit are all easy to set using stepless rotary potentiometers, the same as on the SIRIUS 3RW30/31. The rated motor current, the setting of the tripping time and the resetting of the motor overload function are controlled like the SIRIUS overload relays by means of potentiometers and keys. Once again there is nothing new to get used to.

SIRIUS 3RW40 comes with the new, patented control method called "Polarity Balancing", which is designed to prevent direct current components in two-phase controlled soft starters. On two-phase controlled soft starters the current resulting from superimposition of the two controlled phases flows in the uncontrolled phase. This results for physical reasons in an asymmetric distribution of the three phase currents during the starting operation of the motor. This phenomenon cannot be influenced, but in most applications it is non-critical. Controlling the power semiconductors in the two controlled phases results not only in this asymmetry, however, but also in the previously mentioned direct current components which can cause severe noise generation on the motor at starting voltages of less than 50 %. "Polarity Balancing" reliably eliminates these direct current components during the ramp-up phase. It creates a motor ramp-up that is uniform in speed, torque and current rise. At the same time the acoustic quality of the starting operation comes close to the quality of a three-phase controlled starting operation. This is made possible by the on-going dynamic balancing of current half-waves of different polarity during the motor ramp-up.

The SIRIUS 3RW40 is equipped with optimum functionality. An integral bypass contact system reduces the power loss of the soft starter during operation. This reliably prevents heating of the switchgear environment. Using a 4-step rotary potentiometer it is possible to set different overload tripping times. Thanks to the integral motor overload protection to IEC 60947-4-2 there is no need of an additional overload relay. Device variants with integrated thermistor motor protection (PTC type A of Thermoclick) are available as an option for the sizes S0 to S3. This saves space in the control cabinet and wiring outlay in the feeder. Internal intrinsic device protection prevents in addition the thermal overloading of the thyristors and the power section defects this can cause.

As an option the thyristors can also be protected by SITOR semiconductor fuses from short-circuiting so that the soft starter is still functional after a short-circuit (coordination type 2). And even inrush current peaks are reliably avoided thanks to adjustable current limiting. Three LEDs are used to indicate the operating state as well as possible errors, e.g. non-permissible tripping time (CLASS setting), mains or phase failure, missing load, thermal overloading or device faults.

We offer a comprehensive range of accessories for our soft starters. Examples include box terminal blocks, accessories for mechanical reset and a module for remote reset (size S6 or larger) or a sealing cover or easy-to-fit terminal covers for optimum touch protection.

- Soft starting with voltage ramp; the starting voltage setting range  $U_{\rm S}$  is 40 to 100 % and the ramp time  $t_{\rm R}$  can be set from 0 to 20 s.
- Smooth ramp-down with voltage ramp; the running down time  $t_{\rm off}$  can be set between 0 s to 20 s. The switch-off voltage  $U_{\rm off}$ is then dependent on the selected starting voltage  $U_s$ .
- Solid-state motor overload and intrinsic device protection
- Optional thermistor motor protection (up to size S3)
- Remote reset (integrated up to size S3, optional for size S6 and larger)
- Adjustable current limiting
- Integrated bypass contact system to minimize power loss
- Setting with potentiometers
- Simple mounting and commissioning
- Integrated status monitoring and fault monitoring
- Mains voltages 50/60 Hz, 200 to 600 V
- Various control voltage versions
  - sizes S0 to S3:
  - 24 V AC/DC and
  - 110 ... 230 V AC/DC
- sizes S6 to S12:
  - 115 V AC and 230 V AC.
- Control by way of the internal 24 V DC supply and direct control by means of PLC possible.
- Wide temperature range from -25 to +60 °C
- Built-in auxiliary contacts ensure user-friendly control and possible further processing within the system (for status graphs see Page 6/25)

# 3RW40 for standard applications

#### Technical specifications

 $^{\rm 1)}$  Values for the coil power consumption at +10 %  $U_{\rm n}$ , 50 Hz.

Туре	уре			3RW40 2.	3RW40 2.		10 4.
Control electronics							
Rated values Rated control supply voltage • Tolerance		Terminal A1/A2	V %	24 ±20	110 230 -15/+10	24 ±20	110 230 -15/+10
Rated control supply current  • STANDBY  • During pick-up  • ON without fan  • ON with fan			mA mA mA	< 150 < 200 < 250 < 300	< 50 < 100 < 50 < 70	< 200 < 5000 < 200 < 250	< 50 < 1500 < 50 < 70
Rated frequency • Tolerance			Hz %	50/60 ±10			
Control inputs				ON/OFF			
Rated operational current  • AC  • DC			mA mA	Approx. 12 Approx. 12	3/6 1.5/3	Approx. 12 Approx. 12	3/6 1.5/3
Relay outputs Output 1 Output 2 Output 3 Rated operational current	ON/RUN mode <sup>1)</sup> BYPASSED OVERLOAD/FAILURE	13/14 23/24 95/96/98	A A	Operating indication (NO) Bypass indication (NO) Overload/error indication (NC/NO) 3 AC-15/AC-14 at 230 V, 1 DC-13 at 24 V			
Protection against overvoltages					ans of varistor throug	gh contact	
Short-circuit protection				4 A gL/gG operat 6 A quick (fuse is	tional class; not included in sco	pe of supply)	
1) Factory default: ON mode.							

Туре				3RW40 5.		3RW40 7.	
Control electronics							
Rated values Rated control supply voltage • Tolerance		Terminal A1/A2	V AC %	115 -15/+10	230	115 -15/+10	230
Rated control supply current STAND Rated control supply current ON <sup>1)</sup> Rated frequency • Tolerance	BY		mA mA Hz %	15 440 50/60 ±10	200	15 660 50/60 ±10	360
Control inputs IN Rated operational current Rated operational voltage			mA V DC	ON/OFF Approx. 10 acc. to DIN 19240 24 from internal supply dc+ or external DC supply (acc. to DIN 19240) through terminals and IN			and IN
Relay outputs Output 1 Output 2 Output 3 Rated operational current Protection against overvoltages Short-circuit protection	ON/RUN mode <sup>2)</sup> BYPASSED OVERLOAD/FAILURE	13/14 23/24 95/96/98	A A	4 A gL/gG operation	(NO) lication (NC/NO) 230 V, ns of varistor throug		

Туре	3RW40 2., 3RW40 3.	., 3RW40 4.	
Control electronics			
Operating indications Off Start Bypass Ramp-down	<b>DEVICE</b> Green Green Green Green	STATE/BYPASSED/FAILURE Off Green flashing Green Green flashing	OVERLOAD Off Off Off Off
<b>Alarm signals</b> $I_{\rm e}$ /class setting not permissible Start inhibited/thyristors too hot	Green Yellow flashing	Not relevant Not relevant	Red flashing Off
Error signals  • 24 V: $U < 0.75 \times U_{\rm S}$ or $U > 1.25 \times U_{\rm S}$ • 110 230 V: $U < 0.75 \times U_{\rm S}$ or $U > 1.15 \times U_{\rm S}$ Non-permissible $I_{\rm el}$ (Class setting for edge 0 $->$ 1 on input IN Motor protection shut-down Thermistor motor protection disconnection	Off Off Green Green Green	Red Red Off Off	Off Off Red flashing Red Red flickering
Thermal overloading of the thyristors Missing mains voltage, phase failure, missing load Device fault	Yellow Green Red	Red Red Red	Off Off Off

2) Factory default: ON mode.

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Туре	3RW40 5. and 3RW40 7.			
Control electronics				
Operating indications Off Start Bypass Ramp-down	DEVICE Green Green Green Green	STATE/BYPASSED Off Green flashing Green Green flashing	FAILURE Off Off Off Off	OVERLOAD Off Off Off Off
$ \begin{array}{c} \textbf{Alarm signals} \\ I_{\text{e}} \text{/class setting not permissible} \\ \textbf{Start inhibited/thyristors too hot} \end{array} $	Green Yellow flashing	Not relevant Not relevant	Not relevant Not relevant	Red flashing Off
Error signals $U < 0.75 \times U_{\rm S}$ or $U > 1.15 \times U_{\rm S}$ Non-permissible $I_{\rm e}/{\rm Class}$ setting for edge $0 -> 1$ on input IN Motor protection shut-down	Off Green Green	Off Off Off	Red Red Off	Off Red flashing Red
Thermal overloading of the thyristors Missing mains voltage, phase failure, missing load Device fault	Yellow Green Red	Off Off Off	Red Red Red	Off Off Off

Туре			3RW40			
				Factory default		
Protection functions						
Motor protection functions Trips in the event of Trip class to IEC 60947-4-1 Phase failure sensitivity		Class %	Thermal overloading of the motor 10/15/20 > 40	10		
Overload warning Thermistor protection acc. to IEC 60947-8, type A/IEC Reset option after tripping	0 60947-5-1		No Yes <sup>1)</sup> Manual/automatic/remote reset <sup>2)</sup> (MAN/AUTO/REMOTE <sup>2)</sup> )			
Recovery time		min	5			
Device protection functions Trips in the event of Reset option after tripping			Thermal overloading of the thyristors or bypass Manual/automatic/remote reset <sup>2)</sup>			
Recovery time  • During overloading of the thyristors  • During overloading of the bypass		S S	(MAN/AUTO/REMOTE <sup>2)</sup> ) 30 60			
Control times and parameters						
Control times Closing delay (with connected control voltage) Closing delay (automatic/mains contactor mode) Recovery time (closing command in active ramp-dow		ms ms ms	< 50 < 300 100			
Mains failure bridging time Control supply voltage		ms	50			
Mains failure response time Load current circuit		ms	500			
Reclosing lockout after overload trip Motor protection trip Device protection trip		min	5			
<ul><li>During overloading of the thyristors</li><li>During overloading of the bypass</li></ul>		s s	30 60			
Starting parameters Starting time Starting voltage Starting current limit		s %	0 20 40 100 1.3 5 x I <sub>e</sub>	7.5 40 5 × I <sub>e</sub>		
Ramp-down parameters Ramp-down time		s	020	0		
Reset mode parameters (for motor/device protection Manual reset Automatic reset Remote reset (REMOTE) <sup>2)</sup>	n shut-down) LED LED LED		Off Yellow Green	Off		
Start-up detection			Yes			
Operating mode output 13/14 Rising edge at Falling edge at	Start command Off command Ramp-down end		ON RUN	ON		

<sup>1)</sup> Optional up to size S3 (device variant).

Integrated remote reset (REMOTE) available only for 3RW40 2. to 3RW40 4.; remote reset with 3RU19 accessory module available for 3RW40 5. and 3RW40 7..

Туре			3RW40 2B.5, 3RW40 3B.5, 3RW40 4B.5		3RW40 5BB.5, 3RW40 7BB.5
Power electronics					
Rated operational voltage Tolerance	V AC %	200 480 -15/+10	400 600 -15/+10	200 460 -15/+10	400 600 -15/+10
Rated frequency Tolerance	Hz %	50/60 ±10			
Continuous duty at 40 °C (% of $I_{\Theta}$ )	%	115			
<b>Minimum load</b> (% of set motor current $I_{\rm M}$ )	%	20		15	
Maximum cable length between soft starter and motor	m	300			
Permissible installation height	m	5000 (derating from 100	0, see characteristi	c curves); higher on	request
Permissible mounting position     With auxiliary fan (for 3RW40 2 3RW40 4.)		90° +++++ 90° 22,	5°,22,5° 66		
• Without auxiliary fan (for 3RW40 2 3RW40 4.)		10° 10° 10°	10°	(fan integrated ir	n the soft starter)
Permissible ambient temperature Operation Storage	°C	-25 +60; (derating-40 +80	ng from +40)		
Degree of protection		IP20 for 3RW40 2.; IP00 for 3RW40 3.		IP00	

Туре		3RW40 24	3RW40 26	3RW40 27	3RW40 28
Power electronics					
Load rating with rated operational current I <sub>e</sub> • Acc. to IEC and UL/CSA <sup>1)</sup> , for individual mounting, AC-53a - at 40 °C	А	12.5	25.3	32.2	38
- at 50 °C - at 60 °C	A A	11 10	23 21	29 26	34 31
Smallest adjustable rated motor current $I_{\mathbf{M}}$ For the motor overload protection	А	5	10	17	23
Power loss In operation after completed starting with uninterrupted rated operational current (40 °C) approx.  In operational current (40 °C) approx.	W	2	8	13	19
During starting with current limit set to 300 % $I_{\rm M}$ (40°C)	W	17	47	55	64
Permissible rated motor current and starts per hour					
• For normal starting (Class 10) - rated motor current $I_{\rm M}^{\ 2}$ , starting time 3 s - starts per hour $^{3}$ )	A 1/h	12.5 50	25 23	32 23	38 19
- rated motor current $I_{\rm M}^{\rm 2)4)}$ , starting time 4 s - starts per hour $^{3)}$	A 1/h	12.5 36	25 15	32 16	38 12
• For heavy starting (Class 15) - rated motor current $I_{\rm M}^{\ 2}$ , starting time 4.5 s - starts per hour $^{3)}$	A 1/h	11 49	23 21	30 18	34 18
- rated motor current $I_{\rm M}^{~2)4}$ , starting time 6 s - starts per hour $^{3)}$	A 1/h	11 36	23 14	30 13	34 13
<ul> <li>For heavy starting (Class 20)         <ul> <li>rated motor current I<sub>M</sub><sup>2)</sup>, starting time 6 s</li> <li>starts per hour<sup>3)</sup></li> </ul> </li> </ul>	A 1/h	10 47	21 21	27 20	31 18
- rated motor current $I_{\rm M}^{\rm 2)4)}$ , starting time 8 s - starts per hour $^{3)}$	A 1/h	10 34	21 15	27 14	31 13

 $<sup>^{\</sup>rm 1)}$  Measurement at 60 °C according to UL/CSA not required.

 $<sup>^{2)}\,</sup>$  Current limit on soft starter set to 300 %  $I_{\rm M}.$ 

<sup>3)</sup> For intermittent duty S4 with ON period = 30 %, T<sub>u</sub> = 40 °C, stand-alone installation vertical. The quoted switching frequencies do not apply for automatic mode.

 $<sup>^{\</sup>rm 4)}$  Maximum adjustable rated motor current  $I_{\rm M^{\rm 1}}$  dependent on CLASS setting.

Туре		3RW40 36	3RW40 37	3RW40 38	3RW40 46	3RW40 47
Power electronics				3 10 00	5 10 10	J 10 11
<b>Load rating with rated operational current I<sub>e</sub></b> • Acc. to IEC and UL/CSA <sup>1</sup> ), for individual mounting, AC-53a						
- at 40 °C - at 50 °C	A A	45 42	63 58	72 62,1	80 73	106 98
- at 60 °C	Α	39	53	60	66	90
Smallest adjustable rated motor current $I_{ m M}$ For the motor overload protection	А	23	26	35	43	46
Power loss • In operation after completed starting with uninterrupted rated	W	6	12	15	12	21
operational current (40 °C) approx. • During starting with current limit set to 300 % $I_{\rm M}$ (40°C)	W	79	111	125	144	192
Permissible rated motor current and starts per hour						
• For normal starting (Class 10) - rated motor current $I_{\rm M}^{2}$ , starting time 3 s - starts per hour <sup>3)</sup>	A 1/h	45 38	63 23	72 22	80 22	106 15
- rated motor current $I_{\rm M}^{2)4}$ , starting time 4 s - starts per hour $^{3)}$	A 1/h	45 26	63 15	72 15	80 15	106 10
• For heavy starting (Class 15) - rated motor current $I_{\rm M}^{2}$ ), starting time 4.5 s - starts per hour <sup>3</sup> )	A 1/h	42 30	50 34	56 34	70 24	84 23
- rated motor current $I_{\mathrm{M}}^{(2)4)}$ , starting time 6 s - starts per hour $^{3)}$	A 1/h	42 21	50 24	56 24	70 16	84 17
• For heavy starting (Class 20) - rated motor current $I_{\rm M}{}^{2)}$ , starting time 6 s - starts per hour $^{3)}$	A 1/h	38 30	46 31	50 34	64 23	77 23
- rated motor current $I_{\rm M}^{\rm 2)4)}$ , starting time 8 s - starts per hour $^{\rm 3)}$	A 1/h	38 21	46 22	50 24	64 16	77 16

- $^{\rm 1)}$  Measurement at 60 °C according to UL/CSA not required.
- $^{2)}$  Current limit on soft starter set to 300 %  $I_{\rm M}.$
- $^{3)}$  For intermittent duty S4 with ON period = 30 %,  $T_{\rm u}$  = 40 °C, stand-alone installation vertical. The quoted switching frequencies do not apply for automatic mode.
- $^{4)}$  Maximum adjustable rated motor current  $I_{\mathrm{M}}$ , dependent on CLASS setting.

Туре		3RW40 55	3RW40 56	3RW40 73	3RW40 74	3RW40 75	3RW40 76
Power electronics							
Load rating with rated operational current I <sub>e</sub> • Acc. to IEC and UL/CSA <sup>1)</sup> , for individual mounting, AC-53a							
- at 40 °C - at 50 °C	A A	134 117	162 145	230 205	280 248	356 315	432 385
- at 60 °C	A	100	125	180	215	280	335
Smallest adjustable rated motor current $I_{\mathrm{M}}$ For the motor overload protection	Α	59	87	80	130	131	207
Power loss							
<ul> <li>In operation after completed starting with uninterrupted rated operational current (40 °C) approx.</li> </ul>	W	60	75	75	90	125	165
During starting with current limit set to 350 % <sup>2)</sup> I <sub>M</sub> (40°C)	W	1043	1355	2448	3257	3277	3600
Permissible rated motor current and starts per hour							
• For normal starting (Class 10) - rated motor current $I_{\rm M}^{\ 2)}$ , starting time 10 s - starts per hour $^{3)}$	A 1/h	134 20	162 8	230 14	280 20	356 16	432 17
- rated motor current $I_{\rm M}^{\rm 2)4)}$ , starting time 20 s - starts per hour $^{\rm 3)}$	A 1/h	134 7	162 1.4	230 3	280 8	356 5	432 5
• For heavy starting (Class 15)							
- rated motor current $I_{\rm M}^{(2)}$ , starting time 15 s - starts per hour <sup>3)</sup>	A 1/h	134 11	152 8	210 11	250 13	341 11	402 12
- rated motor current $I_{\rm M}^{\rm 2)4}$ ), starting time 30 s - starts per hour $^{\rm 3)}$	A 1/h	134 1.2	152 1.7	210 1	250 6	341 2	402 2
For heavy starting (Class 20)							
- rated motor current $I_{\rm M}^{(2)}$ , starting time 20 s - starts per hour $^{(3)}$	A 1/h	124 12	142 9	200 10	230 10	311 10	372 10
- rated motor current $I_{\mathrm{M}}^{2)4}$ , starting time 40 s - starts per hour $^{3)}$	A 1/h	124 2	142 2	200 1	230 5	311 1	372 1

- 1) Measurement at 60 °C according to UL/CSA not required.
- $^{2)}$  Current limit on soft starter set to 350 %  $I_{\rm M}.$
- $^{3)}$  For intermittent duty S4 with ON period = 70 %,  $T_{\rm u}$  = 40 °C, stand-alone installation vertical. The quoted switching frequencies do not apply for automatic mode.
- $^{\rm 4)}$  Maximum adjustable rated motor current  $I_{\rm M^{\rm 1}}$  dependent on CLASS setting.

Soft starters	Туре		3RW40 2.	3RW40 3.	3RW40 4.
Conductor cross-sec					
Screw terminals	Main conductor				
Front clamping point connected	• Solid	mm <sup>2</sup>	2 x (1.5 2.5); 2 x (2.5 6) acc. to IEC 60947; max. 1 x 10	2 x (1.5 16)	2 x (2.5 16)
NSB00477	• With end sleeve	mm <sup>2</sup>	2 x (1.5 2.5); 2 x (2.5 6)	1 x (0.75 25)	1 x (2.5 35)
	<ul><li>Stranded</li><li>AWG cables</li></ul>	mm <sup>2</sup>	-	1 x (0.75 35)	1 x (4 70)
	<ul><li>solid or stranded (finely stranded)</li><li>stranded</li></ul>	AWG AWG	2 x (14 10) 1 x 8	1 x (18 2)	2 x (10 1/0)
Rear clamping point connected	• Solid	mm <sup>2</sup>	2 x (1.5 2.5); 2 x (2.5 6) acc. to IEC 60947; max. 1 x 10	2 x (1.5 16)	2 x (2.5 16)
NSB0048	With end sleeve	$\text{mm}^2$	2 x (1.5 2.5); 2 x (2.5 6)	1 x (1.5 25)	1 x (2.5 50)
	<ul><li>Stranded</li><li>AWG cables</li></ul>	mm <sup>2</sup>		1 x (1.5 35)	1 x (10 70)
	<ul><li>solid or stranded (finely stranded)</li><li>stranded</li></ul>	AWG AWG	2 x (14 10) 1 x 8	1 x (16 2)	2 x (10 1/0)
Both clamping points connected	• Solid	mm <sup>2</sup>	2 x (1.5 2.5); 2 x (2.5 6) acc. to IEC 60947; max. 1 x 10	2 x (1.5 16)	2 x (2.5 16)
B00481	With end sleeve	$\mathrm{mm}^2$	2 x (1.5 2.5); 2 x (2.5 6)	2 x (1.5 16)	2 x (2.5 35)
S S	Stranded	$\text{mm}^2$		2 x (1.5 25)	2 x (10 50)
	AWG cables				
	- solid or stranded (finely stranded)	AWG	2 x (14 10)	2 x (16 2)	1 x (10 2/0)
	- stranded	AWG	1 x 8		
	Tightening torque	Nm lb.in	2 2.5 18 22	4.5 40	6.5 58
	Tools		PZ 2	PZ 2	Allen screw 4 mm
	Degree of protection		IP20	IP20 (IP00 terminal compartment)	IP20 (IP00 terminal compartment)
Spring-loaded terminals	Main conductor			,	, ,
=	• Solid	$\text{mm}^2$	1 10		
	• Finely stranded with end sleeve	mm <sup>2</sup>	1 6 end sleeves without plastic collar		
	AWG cables				
	- solid or stranded (finely stranded)	AWG	16 10		
	- stranded	AWG	1 x 8		
	Tools		DIN ISO 2380-1A0; 5 x 3		
	Degree of protection		IP20		
Busbar connections	Main conductor				
	With cable lug acc. to DIN 46234 or max. 20 mm wide				
	- stranded	$\text{mm}^2$			2 x (10 70)
	- finely stranded	$\text{mm}^2$			2 x (10 50)
	AWG cables, solid or stranded	AWG			2 x (7 1/0)

Soft starters	Туре	_	3RW40 5.	3RW40 7.
Conductor cross-section			3NW40 3.	3NW40 7.
Screw terminals	Main conductors:			
With box terminal	main conductors.		3RT19 55-4G (55 kW)	3RT19 66-4G
Front clamping point connected	Finely stranded with end sleeve     Finely stranded without end sleeve     Stranded	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup>	16 70 16 70	70 240 70 240 95 300
NSB00479	<ul> <li>Ribbon cable conductors (number x width x thickness)</li> <li>AWG cables, solid or stranded</li> </ul>	mm AWG	Min. 3 x 9 x 0.8 Max. 6 x 15.5 x 0.8 6 2/0	Min. 6 x 9 x 0.8 Max. 20 x 24 x 0.5 3/0 600 kcmil
Rear clamping point connected	Finely stranded with end sleeve     Finely stranded without end sleeve     Stranded	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup>	16 70 16 70 16 70	120 185 120 185 120 240
NSB00480	<ul> <li>Ribbon cable conductors (number x width x thickness)</li> <li>AWG cables, solid or stranded</li> </ul>	mm AWG	Min. 3 x 9 x 0.8 Max. 6 x 15.5 x 0.8 6 2/0	Min. 6 x 9 x 0.8 Max. 20 x 24 x 0.5 250 500 kcmil
Both clamping points connected	Finely stranded with end sleeve     Finely stranded without end sleeve     Stranded	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup>	Max. 1 x 50, 1 x 70 Max. 1 x 50, 1 x 70 Max. 2 x 70	Min. 2 x 50; max. 2 x 185 Min. 2 x 50; max. 2 x 185 Max. 2 x 70; max. 2 x 240
300481	<ul> <li>Ribbon cable conductors (number x width x thickness)</li> <li>AWG cables, solid or stranded</li> </ul>	mm AWG	Max. 2 x (6 x 15.5 x 0.8)  Max. 2 x 1/0	Max. 2 x (20 x 24 x 0.5)  Min. 2 x 2/0 Max. 2 x 500 kcmil
95 2	Terminal screws     tightening torque	Nm lb.in	M10 (hexagon socket, A/F4) 10 12 90 110	M12 (hexagon socket, A/F5) 20 22 180 195
Screw terminals	Main conductors:			
With box terminal			3RT19 56-4G	
Front or rear clamping point connected	<ul><li>Finely stranded with end sleeve</li><li>Finely stranded without end sleeve</li><li>Stranded</li></ul>	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup>	16 120 16 120 16 120	
NSB00479	Ribbon cable conductors (number x width x thickness) AWG cables, solid or stranded	mm AWG	Min. 3 x 9 x 0.8 max. 6 x 15.5 x 0.8 6 250 kcmil	
Both clamping points connected	Finely stranded with end sleeve     Finely stranded without end sleeve     Stranded	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup>	Max. 1 x 95, 1 x 120 Max. 1 x 95, 1 x 120 Max. 2 x 120	
NSB00481	<ul> <li>Ribbon cable conductors (number x width x thickness)</li> <li>AWG cables, solid or stranded</li> </ul>	mm AWG	Max. 2 x (10 x 15.5 x 0.8)  Max. 2 x 3/0	
Screw terminals	Main conductors:			
	Without box terminal/busbar connection			
	<ul> <li>Finely stranded with cable lug</li> <li>Stranded with cable lug</li> <li>AWG cables, solid or stranded</li> </ul>	mm <sup>2</sup> mm <sup>2</sup> AWG	16 95 <sup>1)</sup> 25 120 <sup>1)</sup> 4 250 kcmil	50 240 <sup>2)</sup> 70 240 <sup>2)</sup> 2/0 500 kcmil
	Connecting bar (max. width)     Terminal screws     tightening torque	mm Nm Ib.in	17 M8 x 25 (A/F13) 10 14 89 124	25 M10 x 30 (A/F17) 14 24 124 210

When connecting cable lugs to DIN 46235, use 3RT19 56-4EA1 terminal cover for conductor cross-sections from 95 mm<sup>2</sup> to ensure phase spacing.

When connecting cable lugs to DIN 46234, the 3RT19 66-4EA1 terminal cover must be used for conductor cross-sections of 240 mm² and more as well as DIN 46235 for conductor cross-sections of 185 mm² and more to keep the phase clearance.

Soft starters	Туре		3RW40
Conductor cross-sec	ctions		
Auxiliary conductors (1	or 2 conductors can be connected):		
	Screw terminals		
	<ul><li>Solid</li><li>Finely stranded with end sleeve</li></ul>	mm <sup>2</sup> mm <sup>2</sup>	2 x (0.5 2.5) 2 x (0.5 1.5)
	<ul> <li>AWG cables</li> <li>solid or stranded</li> <li>finely stranded with end sleeve</li> </ul>	AWG AWG	2 x (20 14) 2 x (20 16)
	<ul><li>Terminal screws</li><li>tightening torque</li></ul>	Nm Ib.in	0,8 1.2 7 10.3
	Spring-loaded terminals		
	<ul> <li>Solid</li> <li>3RW40 2 3RW40 4.</li> <li>3RW40 5., 3RW40 7.</li> <li>Finely stranded with end sleeve</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	2 x (0.25 2.5) 2 x (0.25 1.5) 2 x (0.25 1.5)
	<ul> <li>AWG cables, solid or stranded</li> </ul>	AWG	2 x (24 14) for 3RW40 2 3RW40 4.; 2 x (24 16) for 3RW40 5. and 3RW40 7.

	Standard	Parameters
Electromagnetic compatibility acc. to EN 60947-4-2		
EMC interference immunity		
Electrostatic discharge (ESD)	EN 61000-4-2	±4 kV contact discharge, ±8 kV air discharge
Electromagnetic RF fields	EN 61000-4-3	Frequency range: 80 1000 MHz with 80 % at 1 kHz Degree of severity 3: 10 V/m
Conducted RF interference	EN 61000-4-6	Frequency range: 150 kHz 80 MHz with 80 % at 1 kHz Interference 10 V
RF voltages and RF currents on cables		
• Burst	EN 61000-4-4	±2 kV/5 kHz
• Surge	EN 61000-4-5	±1 kV line to line ±2 kV line to earth
EMC interference emission		
EMC interference field strength	EN 55011	Limit value of Class A at 30 1000 MHz, limit value of Class B with 3RW40 2. 24 V AC/DC
Radio interference voltage	EN 55011	Limit value of Class A at 0.15 30 MHz, limit value of Class B with 3RW40 2. 24 V AC/DC
Is an RI suppression filter necessary?		
Degree of noise suppression A (industrial applications)	No	
Degree of noise suppression B (applications for residential areas) Control voltage • 230 V AC/DC • 24 V AC/DC	Not available <sup>1)</sup> No for 3RW40 2.; yes for 3RW40 3.	and 3RW40 4.

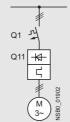
Degree of noise suppression B cannot be obtained through the use of filters as the strength of the electromagnetic field is not attenuated by the filter.

# 3RW40 for standard applications

#### Fuse assignment

The type of coordination to which the motor feeder with soft starter is mounted depends on the application-specific requirements. Normally, fuseless mounting (combination of motor starter protector/circuit breaker and soft starter) is sufficient. If type of coordination "2" is to be fulfilled, semiconductor fuses must be fitted in the motor feeder.

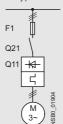
#### **Fuseless version**



Soft starters		Motor starter protect	tors/circuit br	eakers <sup>1)</sup>			
	Rated current	400 V +10 %		Rated current	575 V +10 %		Rated current
Q11		Q1	$I_{ m qmax}$		Q1	$I_{ m qmax}$	
Туре	Α	Туре	kA	Α	Туре	kA	A
Type of coord	dination "1" <sup>2</sup> )						
3RW40 24 3RW40 26 3RW40 27 3RW40 28	12.5 25 32 38	3RV1 031-4AA10 3RV1 031-4DA10 3RV1 031-4EA10 3RV1 031-4FA10	55 55 55 55	16 25 32 40	  	  	  
3RW40 36 3RW40 37 3RW40 38	45 63 72	3RV1 031-4GA10 3RV1 041-4JA10 3RV1 041-4KA10	20 20 20	45 63 75	 	 	  
3RW40 46 3RW40 47	80 106	3RV1 041-4LA10 3RV1 041-4MA10	11 11	90 100	 		 
3RW40 55 3RW40 56	134 162	3VL3 720-2DC36 3VL3 720-2DC36	35 35	200 200	3VL3 720-1DC36 3VL3 720-1DC36	12 12	200 200
3RW40 73 3RW40 74 3RW40 75 3RW40 76	230 280 356 432	3VL4 731-2DC36 3VL4 731-2DC36 3VL4 740-2DC36 3VL5 750-2DC36	65 65 65 65	315 315 400 500	3VL5 731-3DC36 3VL5 731-3DC36 3VL5 740-3DC36 3VL5 750-3DC36	35 35 35 35	315 315 400 500

<sup>1)</sup> The rated motor current must be considered when selecting the devices.

#### Fused version (line protection only)



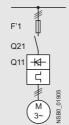
		3 8			
Soft starters		Line protection,	maximum		Line contactor
	Rated cur- rent		Rated current	Size	(optional)
Q11		F1			Q21
Type	A	Туре	A		
Type of coord	dination "1" <sup>1)</sup> :	I <sub>q</sub> = 65 kA at 600	V +5 %		
3RW40 24 3RW40 26 3RW40 27 3RW40 28	12.5 25 32 38	3NA3 820-6 3NA3 822-6 3NA3 824-6 3NA3 824-6	50 63 80 80	00 00 00 00	3RT10 24 3RT10 26 3RT10 34 3RT10 35
3RW40 36 3RW40 37 3RW40 38	45 63 72	3NA3 130-6 3NA3 132-6 3NA3 132-6	100 125 125	1 1 1	3RT10 36 3RT10 44 3RT10 45
3RW40 46 3RW40 47	80 106	3NA3 136-6 3NA3 136-6	160 160	1 1	3RT10 45 3RT10 46
3RW40 55 3RW40 56	134 162	3NA3 244-6 3NA3 244-6	250 250	2	3RT10 55-6A.36 3RT10 56-6A.36
3RW40 73 3RW40 74 3RW40 75 3RW40 76	230 280 356 432	2 x 3NA3 354-6 2 x 3NA3 354-6 2 x 3NA3 365-6 2 x 3NA3 365-6	2 x 355 2 x 355 2 x 500 2 x 500	3 3 3 3	3RT10 65-6A.36 3RT10 66-6A.36 3RT10 75-6A.36 3RT10 76-6A.36

<sup>1)</sup> The types of coordination are explained in more detail under "Fuseless Load Feeders" on Page 6/58.

The types of coordination are explained in more detail under "Fuseless Load Feeders" on Page 6/58.

3RW40 for standard applications

#### Fused version with 3NE1 SITOR fuses (semiconductor and line protection)



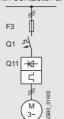
		3 8			
Soft starter	's	All-range fuses			Line contactor
	Rated current		Rated current	Size	(optional)
Q11	^	F'1	^		Q21
Туре	Α	Type	A		
Type of coo	ordination "2	2" <sup>1)</sup> : I <sub>q</sub> = 65 kA at 600	V +5 %		
3RW40 24 3RW40 26 3RW40 27 3RW40 28	12.5 25 32 38	3NE1 814-0 3NE1 803-0 3NE1 020-2 3NE1 020-2	20 35 80 80	000 000 00 00	3RT10 24 3RT10 26 3RT10 34 3RT10 35
3RW40 36 3RW40 37 3RW40 38	45 63 72	3NE1 020-2 3NE1 820-0 3NE1 820-0	80 80 80	00 000 000	3RT10 36 3RT10 44 3RT10 45
3RW40 46 3RW40 47	80 106	3NE1 021-0 3NE1 022-0	100 125	00 00	3RT10 45 3RT10 46
3RW40 55 3RW40 56	134 162	3NE1 227-2 3NE1 227-2	250 250	1 1	3RT10 55-6A.36 3RT10 56-6A.36
3RW40 73 3RW40 74 3RW40 75 3RW40 76	230 280 356 432	3NE1 331-2 3NE1 333-2 3NE1 334-2 3NE1 435-2	350 450 500 560	2 2 2 3	3RT10 65-6A.36 3RT10 66-6A.36 3RT10 75-6A.36 3RT10 76-6A.36

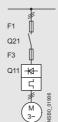
<sup>1)</sup> The types of coordination are explained in more detail under "Fuseless Load Feeders" on Page 6/58. The type of coordination "2" refers only to soft starters, not to any components in the feeder.

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# 3RW40 for standard applications

Fused version with 3NE3 SITOR fuses (semiconductor protection by fuse, line and overload protection by motor starter protector/circuit breaker; alternatively, installation with contactor and overload relay possible)





Soft starte	ers	Semiconductor fuses, minimum			Semiconductor fuses, maximum			Semiconductor fuses, minimum		
	Rated current		Rated current	Size		Rated current	Size		Rated current	Size
Q11		F3			F3			F3		
Туре	А	Type	Α		Туре	Α		Туре	Α	
Type of co	ordination "2	$I_{q} = 65 \text{ kA a}$	t 600 V +5 %							
3RW40 24	12.5							3NE4 101	32	0
3RW40 26	25				3NE3 221	100	1	3NE4 102	40	0
3RW40 27	32				3NE3 224	160	1	3NE4 118	63	0
3RW40 28	38				3NE3 224	160	1	3NE4 118	63	0
3RW40 36	45				3NE3 224	160	1	3NE4 120	80	0
3RW40 37	63				3NE3 225	200	1	3NE4 121	100	0
3RW40 38	72	3NE3 221	100	1	3NE3 227	250	1			
3RW40 46	80	3NE3 222	125	1	3NE3 225	200	1			
3RW40 47	106	3NE3 224	160	1	3NE3 231	350	1			
3RW40 55	134	3NE3 227	250	1	3NE3 335	560	2			
3RW40 56	162	3NE3 227	250	1	3NE3 335	560	2			
3RW40 73	230	3NE3 232-0B	400	1	3NE3 333	450	2			
3RW40 74	280	3NE3 233	450	1	3NE3 336	630	2			
3RW40 75	356	3NE3 335	560	2	3NE3 336	630	2			
3RW40 76	432	3NE3 337-8	710	2	3NE3 340-8	900	2			

Soft starters		Semicondu	Semiconductor fuses max.			Semiconductor fuses min.			Semiconductor fuses max.			Cylindrical fuses	
		Rated current		Rated current	Size		Rated current	Size		Rated current	Size		Rated current
Q11 Type		А	F3 Type	A		F3 Type	A		F3 Type	A		F3 Type	А
Туре	of co	ordination "2	$I^{(1)}: I_{q} = 65 $	A at 600 V +5	%								
3RW 3RW 3RW	40 24 40 26 40 27 40 28	12.5 25 32 38	3NE4 117 3NE4 117 3NE4 118 3NE4 118	50 50 63 63	0 0 0 0	3NE8 015-1 3NE8 017-1 3NE8 018-1 3NE8 020-1	25 50 63 80	00 00 00 00	3NE8 017-1 3NE8 021-1 3NE8 022-1 3NE8 024-1	50 100 125 160	00 00 00 00	3NC2 240 3NC2 263 3NC2 280 3NC2 280	63 80
3RW	40 36 40 37 40 38	45 63 72	3NE4 120 3NE4 121	80 100 	0 0 	3NE8 020-1 3NE8 021-1 3NE8 022-1	80 100 125	00 00 00	3NE8 024-1 3NE8 024-1 3NE8 024-1	160 160 160	00 00 00	3NC2 280  	80  
	40 46 40 47	80 106				3NE8 022-1 3NE8 024-1	125 160	00 00	3NE8 024-1 3NE8 024-1	160 160	00 00		 
	40 55 40 56	134 162					 			 			 
3RW	40 73 40 74 40 75	230 280 356	 	  	  	  	  	 	  	  	  	  	  
3RW	40 76	432											

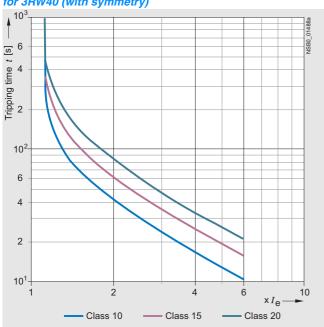
Soft starter	rs	Line contactor	Motor starter prot	ectors/circuit b	oreakers		Line protection,	maximum	
	Rated current	(optional)	400 V +10 %	Rated current	575 V +10 %	Rated current		Rated current	Size
Q11 Type	А	Q21	Q1 Type	А	Q1 Type	А	F1 Type	А	
Type of coo	ordination "2	$I_{q}^{(1)}$ : $I_{q}$ = 65 kA at 6	600 V +5 %						
3RW40 24 3RW40 26 3RW40 27 3RW40 28	12.5 25 32 38	3RT10 24 3RT10 26 3RT10 34 3RT10 35	3RV1 031-4AA10 3RV1 031-4DA10 3RV1 031-4EA10 3RV1 031-4FA10	55 55 55 55	  	  	3NA3 820-6 3NA3 822-6 3NA3 824-6 3NA3 824-6	50 63 80 80	00 00 00 00
3RW40 36 3RW40 37 3RW40 38	45 63 72	3RT10 36 3RT10 44 3RT10 45	3RV1 031-4GA10 3RV1 041-4JA10 3RV1 041-4KA10	20 20 20	  	  	3NA3 130-6 3NA3 132-6 3NA3 132-6	100 125 125	1 1 1
3RW40 46 3RW40 47	80 106	3RT10 45 3RT10 46	3RV1 041-4LA10 3RV1 041-4MA10	11 11			3NA3 136-6 3NA3 136-6	160 160	1 1
3RW40 55 3RW40 56	134 162	3RT10 55-6A.36 3RT10 56-6A.36	3VL3 720-1DC36 3VL3 720-1DC36	200 200	3VL3 720-1DC36 3VL3 720-1DC36	200 200	3NA3 244-6 3NA3 244-6	250 250	2
3RW40 73 3RW40 74 3RW40 75 3RW40 76	230 280 356 432	3RT10 65-6A.36 3RT10 66-6A.36 3RT10 75-6A.36 3RT10 76-6A.36	3VL4 731-1DC36 3VL4 731-1DC36 3VL4 740-1DC36 3VL5 750-1DC36	315 315 400 500	3VL5 731-1DC36 3VL5 731-1DC36 3VL5 740-1DC36 3VL5 750-1DC36	315 315 400 500	2 x 3NA3 354-6 2 x 3NA3 354-6 2 x 3NA3 365-6 2 x 3NA3 365-6	2 x 355 2 x 355 2 x 500 2 x 500	3 3 3 3

<sup>1)</sup> The types of coordination are explained in more detail under "Fuseless Load Feeders" on Page 6/58. The type of coordination "2" refers only to soft starters, not to any components in the feeder.

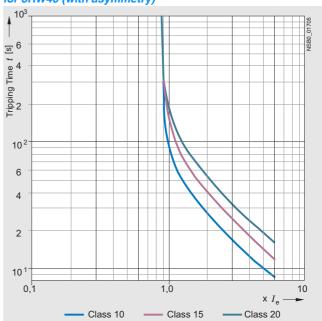
3RW40 for standard applications

#### Characteristic curves

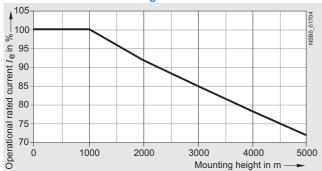
# Motor protection tripping characteristics for 3RW40 (with symmetry)



# Motor protection tripping characteristics for 3RW40 (with asymmetry)



#### Permissible installation height



At an installation height above 2000 m, the max. permissible operational voltage is reduced to 460 V.

#### 3RW40 for standard applications

#### More information

#### Application examples for normal starting (Class 10)

Normal starting Class 10 (up to 20 s with 350 %  $I_{\rm n\,motor}$ ). The soft starter rating can be selected to be as high as the rating of the motor used.

Application		Conveyor belt	Roller conveyor	Compressor	Small fan	Pump	Hydraulic pump
Starting parameters							
<ul> <li>Voltage ramp and current limiting</li> </ul>							
<ul> <li>starting voltage</li> </ul>	%	70	60	50	40	40	40
- starting time	S	10	10	10	10	10	10
<ul> <li>current limit value</li> </ul>		$5 \times I_{M}$	$5 \times I_{M}$	$4 \times I_{M}$	$4 \times I_{M}$	$4 \times I_{M}$	$4 \times I_{M}$
Ramp-down time	S	5	5	0	0	10	0

#### Application examples for heavy starting (Class 20)

Heavy starting Class 20 (up to 40 s with 350 %  $I_{\rm n\ motor}$ ),
The soft starter has to be selected at least one rating class higher than the motor used.

Application		Stirrer	Centrifuge
Starting parameters			
Voltage ramp and current limiting     starting voltage     starting time     current limit value	% S	40 20 4 × I <sub>M</sub>	40 20 4 x <i>I</i> <sub>M</sub>
Ramp-down time		0	0

These tables present sample set values and device sizes. They are intended only for the purposes of information and are not binding. The set values depend on the application in question and must be optimized during commissioning.

The soft starter dimensions should be checked where necessary with the Win-Soft Starter software or with the help of Technical Assistance.

3RW40 for standard applications

#### Configuration

The 3RW solid-state soft starters are designed for easy starting conditions. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. For accurate dimensioning, use the Win-Soft Starter selection and simulation program.

Where long starting times are involved, the integrated solid-state overload relay for heavy starting should not be disconnected. PTC sensors are recommended. This also applies for the smooth ramp-down because during the ramp-down time an additional current loading applies in contrast to free ramp-down.

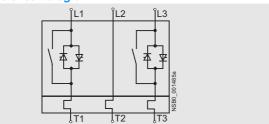
In the motor feeder between the SIRIUS 3RW soft starter and the motor, no capacitive elements are permitted (e.g. no reactive-power compensation equipment). In addition, neither static systems for reactive-power compensation nor dynamic PFC (Power Factor Correction) must be operated in parallel during starting and ramp-down of the soft starter. This is important to prevent faults arising on the compensation equipment and/or the soft starter.

All elements of the main circuit (such as fuses and controls) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, controls and overload relays must be ordered separately. Please observe the maximum switching frequencies specified in the technical specifications.

#### Note.

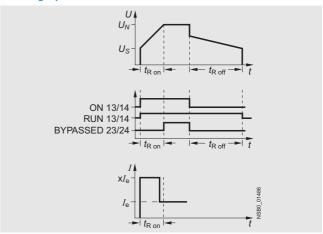
When induction motors are switched on, voltage drops occur as a rule on starters of all types (direct starters, wye-delta starters, soft starters). The infeed transformer must always be dimensioned such that the voltage dip when starting the motor remains within the permissible tolerance. If the infeed transformer is dimensioned with only a small margin, it is best for the control voltage to be supplied from a separate circuit (independently of the main voltage) in order to avoid the potential switching off of the soft starter.

#### Schematic circuit diagram



A bypass contact system and solid-state overload relay are already integrated in the 3RW40 soft starter and therefore do not have to be ordered separately.

#### Status graphs



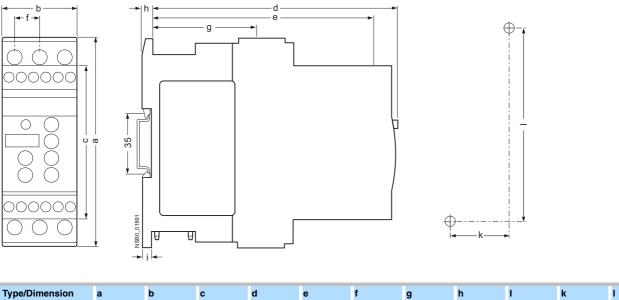
#### Win-Soft Starter selection and simulation program

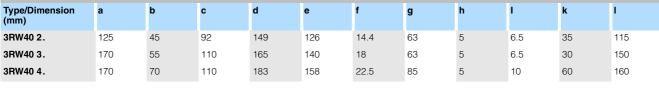
With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

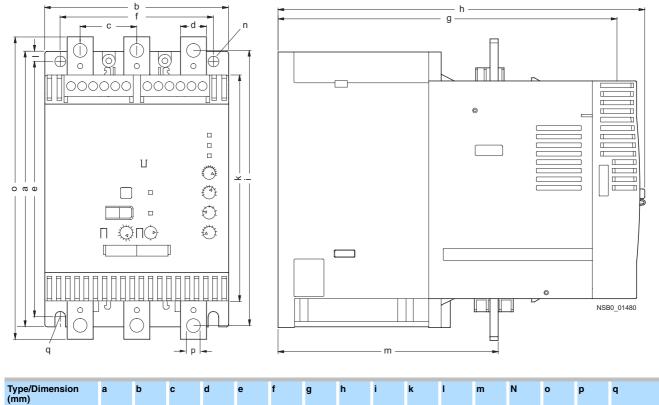
The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

You can order the CD-ROM under the following order number: Order No. E20001-D1020-P302-V2-7400.

More information can be found on the Internet at http://www.siemens.com/softstarter







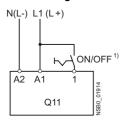
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### **3RW Soft Starters**

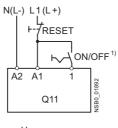
#### **Project planning aids**

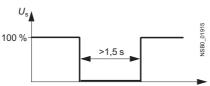
#### 3RW40 2. ... 3RW40 4. connection examples for control circuit

#### Control using switches

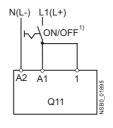


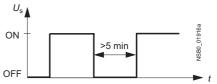
#### With remote reset



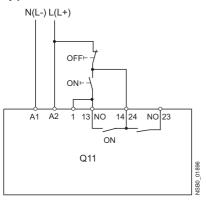


#### **Automatic mode**





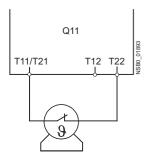
#### Control of 3RW40 2. ... 3RW40 4. by pushbutton

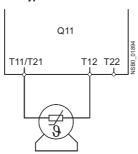


# Connection example of 3RW40 2. ... 3RW40 4. for PTC sensors (thermistor motor protection)

#### Thermoclick

#### PTC type A





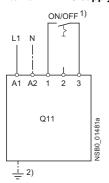
#### 1) Caution: Risk of restarting

When operating with a switch (ON/OFF) a new, automatic restart will take place automatically if the start command is still active at terminal 1.

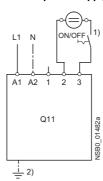
#### **Project planning aids**

#### 3RW40 5. and 3RW40 7. connection examples for control circuit

# Control by switch using internal 24 V DC supply

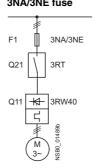


#### external power supply

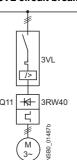


# 3RW40 – 3-phase motor with 3NA/3NE fuse

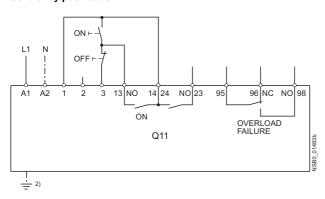
3RW40 connection examples for main circuit<sup>3)</sup>



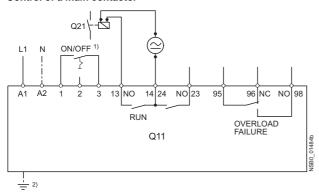
# 3RV motor starter protectors/ 3VL circuit breakers



#### Control by pushbutton



#### Control of a main contactor



 Caution: Risk of restarting
 When operating with a switch (ON/OFF) a new, automatic restart will take place automatically if the start command is still active at terminal 3.

- $^{2)}\,$  Grounding necessary for fan connection to 3RW40 5...
- $^{\rm 3)}\,$  As an alternative, the motor feeder can also be installed as a fuseless or as a fused version. For fuse and switching device coordination, cal specifications
  - The wiring diagrams are provided only as examples.